

WAIFI — July 16–19 , 2012

Finding Optimal Formulae for Bilinear Maps

Razvan Barbulescu Jérémie Detrey Nicolas Estibals
Paul Zimmermann

CAMEL project-team, LORIA
University of Lorraine, INRIA, CNRS



A bit of history

- ▶ Multiplication is an **expensive** arithmetic operation
- ▶ Well-studied problem
 - **Karatsuba** (1962)
 - Toom–Cook (1963), **evaluation-interpolation** schemes
 - **CRT**-based algorithms
 - **Schönhage–Strassen** algorithm (1971)
 - ...
- ▶ *Five-, six-, and seven-term Karatsuba-like formulae*, P. Montgomery (2005)
 - **ad-hoc** formulae
 - **partly exhaustive search** for five-, six- and seven-term multiplication
 - successfully used in practice in the M4RIE library (Albrecht, 2011)

Outline of the talk

- ▶ Problem description
- ▶ Resolution methods
- ▶ Results

Outline of the talk

- ▶ Problem description
- ▶ Resolution methods
- ▶ Results

Example: a 2-term polynomial times a 3-term one

► We want to compute

$$\begin{aligned} C(X) &= (a_1 \cdot X + a_0) \times (b_2 \cdot X^2 + b_1 \cdot X + b_0) \\ &= a_1 b_2 \cdot X^3 + (a_1 b_1 + a_0 b_2) \cdot X^2 + (a_0 b_1 + a_1 b_0) \cdot X + a_0 b_0 \end{aligned}$$

Example: a 2-term polynomial times a 3-term one

- ▶ We want to compute

$$\begin{aligned}C(X) &= (a_1 \cdot X + a_0) \times (b_2 \cdot X^2 + b_1 \cdot X + b_0) \\ &= a_1 b_2 \cdot X^3 + (a_1 b_1 + a_0 b_2) \cdot X^2 + (a_0 b_1 + a_1 b_0) \cdot X + a_0 b_0\end{aligned}$$

- ▶ Only 5 products required instead of 6
 - use Karatsuba's trick

$$C(X) = a_1 b_2 \cdot X^3 + (a_1 b_1 + a_0 b_2) \cdot X^2 + ((a_0 + a_1)(b_0 + b_1) - a_1 b_1 - a_0 b_0) \cdot X + a_0 b_0$$

Example: a 2-term polynomial times a 3-term one

- ▶ We want to compute

$$\begin{aligned}C(X) &= (a_1 \cdot X + a_0) \times (b_2 \cdot X^2 + b_1 \cdot X + b_0) \\ &= a_1 b_2 \cdot X^3 + (a_1 b_1 + a_0 b_2) \cdot X^2 + (a_0 b_1 + a_1 b_0) \cdot X + a_0 b_0\end{aligned}$$

- ▶ Only 5 products required instead of 6
 - use Karatsuba's trick

$$C(X) = a_1 b_2 \cdot X^3 + (a_1 b_1 + a_0 b_2) \cdot X^2 + ((a_0 + a_1)(b_0 + b_1) - a_1 b_1 - a_0 b_0) \cdot X + a_0 b_0$$

- compute the products

$$\begin{aligned}g_0 &= a_0 \cdot b_0, \\ g_1 &= a_0 \cdot b_2, \\ g_2 &= a_1 \cdot b_1, \\ g_3 &= a_1 \cdot b_2, \text{ and} \\ g_4 &= (a_0 + a_1) \cdot (b_0 + b_1).\end{aligned}$$

- reconstruct the result

$$C(X) = g_3 \cdot X^3 + (g_1 + g_2) \cdot X^2 + (g_4 - g_2 - g_0) \cdot X + g_0$$

General form of a multiplication formula

- ▶ We want to compute, over a given field K (or any K -algebra \mathbf{K}),

$$(a_{n-1} \cdot X^{n-1} + \cdots + a_0) \times (b_{m-1} \cdot X^{m-1} + \cdots + b_0) = c_{n+m-2} \cdot X^{n+m-2} + \cdots + c_0$$

- ▶ All formulae for multiplication can be expressed as:

- compute some linear combinations of the a_i 's

$$a'_j = \sum \alpha_{i,j} \cdot a_i$$

- compute some linear combinations of the b_i 's

$$b'_j = \sum \beta_{i,j} \cdot b_i$$

- perform some products

$$g_j = a'_j \cdot b'_j$$

General form of a multiplication formula

- ▶ We want to compute, over a given field K (or any K -algebra \mathbf{K}),

$$(a_{n-1} \cdot X^{n-1} + \cdots + a_0) \times (b_{m-1} \cdot X^{m-1} + \cdots + b_0) = c_{n+m-2} \cdot X^{n+m-2} + \cdots + c_0$$

- ▶ All formulae for multiplication can be expressed as:

- compute some linear combinations of the a_i 's

$$a'_j = \sum \alpha_{i,j} \cdot a_i$$

- compute some linear combinations of the b_i 's

$$b'_j = \sum \beta_{i,j} \cdot b_i$$

- perform some products

$$g_j = a'_j \cdot b'_j$$

- reconstruct the result by linear combinations of the products

$$c_k = \sum \gamma_{j,k} \cdot g_j$$

General form of a multiplication formula

- We want to compute, over a given field K (or any K -algebra \mathbf{K}),

$$(a_{n-1} \cdot X^{n-1} + \cdots + a_0) \times (b_{m-1} \cdot X^{m-1} + \cdots + b_0) = c_{n+m-2} \cdot X^{n+m-2} + \cdots + c_0$$

- All formulae for multiplication can be expressed as:

- compute some linear combinations of the a_i 's

$$a'_j = \sum \alpha_{i,j} \cdot a_i, \quad \text{with } \alpha_{i,j} \in K$$

- compute some linear combinations of the b_i 's

$$b'_j = \sum \beta_{i,j} \cdot b_i, \quad \text{with } \beta_{i,j} \in K$$

- perform some products

$$g_j = a'_j \cdot b'_j, \quad \text{with } a'_j, b'_j \in \mathbf{K}$$

- reconstruct the result by linear combinations of the products

$$c_k = \sum \gamma_{j,k} \cdot g_j, \quad \text{with } \gamma_{j,k} \in K$$

General form of a multiplication formula

- ▶ We want to compute, over a given field K (or any K -algebra \mathbf{K}),

$$(a_{n-1} \cdot X^{n-1} + \cdots + a_0) \times (b_{m-1} \cdot X^{m-1} + \cdots + b_0) = c_{n+m-2} \cdot X^{n+m-2} + \cdots + c_0$$

- ▶ All formulae for multiplication can be expressed as:

- compute some linear combinations of the a_i 's

$$a'_j = \sum \alpha_{i,j} \cdot a_i, \quad \text{with } \alpha_{i,j} \in K$$

- compute some linear combinations of the b_i 's

$$b'_j = \sum \beta_{i,j} \cdot b_i, \quad \text{with } \beta_{i,j} \in K$$

- perform some products

$$g_j = a'_j \cdot b'_j, \quad \text{with } a'_j, b'_j \in \mathbf{K}$$

- reconstruct the result by linear combinations of the products

$$c_k = \sum \gamma_{j,k} \cdot g_j, \quad \text{with } \gamma_{j,k} \in K$$

- ▶ This is also valid for any bilinear map

$$F : \quad K^n \quad \times \quad K^m \quad \longrightarrow \quad K^\ell \\ ((a_0, \dots, a_{n-1}) , (b_0, \dots, b_{m-1})) \longmapsto (c_0, \dots, c_{\ell-1})$$

Formal framework

$$F : K^n \times K^m \rightarrow K^\ell$$

Formal framework

$$F : K^n \times K^m \rightarrow K^\ell$$

- ▶ Represent the products and the coefficients of the result as elements of the nm -dimensional K -vector space

$$V = \text{Span } \mathcal{V}, \quad \text{with basis } \mathcal{V} = \{a_i b_j\}_{0 \leq i < n, 0 \leq j < m},$$

where the $a_i b_j$'s are seen as formal elements

Formal framework

$$F : K^n \times K^m \rightarrow K^\ell$$

- ▶ Represent the products and the coefficients of the result as elements of the nm -dimensional K -vector space

$$V = \text{Span } \mathcal{V}, \quad \text{with basis } \mathcal{V} = \{a_i b_j\}_{0 \leq i < n, 0 \leq j < m},$$

where the $a_i b_j$'s are seen as formal elements

- ▶ **Target vectors:** the coefficients of the result form a set

$$\mathcal{T} = \{c_i\}_{0 \leq i < \ell} \subset V$$

Formal framework

$$F : K^n \times K^m \rightarrow K^\ell$$

- ▶ Represent the products and the coefficients of the result as elements of the nm -dimensional K -vector space

$$V = \text{Span } \mathcal{V}, \quad \text{with basis } \mathcal{V} = \{a_i b_j\}_{0 \leq i < n, 0 \leq j < m},$$

where the $a_i b_j$'s are seen as formal elements

- ▶ **Target vectors:** the coefficients of the result form a set

$$\mathcal{T} = \{c_i\}_{0 \leq i < \ell} \subset V$$

- ▶ **Generators:** the set $\mathcal{G} \subset V$ of the **potential products** to use in a formula

$$\mathcal{G} = \{(\sum \alpha_i a_i) \cdot (\sum \beta_j b_j) \mid \forall i, \alpha_i \in K \text{ and } \forall j, \beta_j \in K\}$$

If $g = \lambda g'$ for some scalar λ , we keep only one.

Problem definition

Definition

Given:

1. a finite dimensional vector space V ,
2. a finite set \mathcal{G} generating V and
3. a finite set of vectors \mathcal{T} ,

find the minimal number k of generators which span \mathcal{T} .

- ▶ The problem can be formulated as the bilinear rank problem, which is known to be NP-hard.
- ▶ Searching formulae for polynomial and matrix multiplication are particular instances (NP-hard?).

Example (continued)

Consider the previous example: 2×3 -term polynomial product in $\mathbb{F}_2[X]$

- ▶ V is a 6-dimensional vector space with basis

$$\mathcal{V} = \{a_0b_0, a_0b_1, a_0b_2, a_1b_0, a_1b_1, a_1b_2\}$$

- ▶ The set of targets is

$$\mathcal{T} = \{a_1b_2, a_1b_1 + a_0b_2, a_0b_1 + a_1b_0, a_0b_0\}$$

- ▶ The set of generators contains 21 products:

$$\mathcal{G} = \left\{ \begin{array}{lll} a_0 \cdot b_0, & a_1 \cdot b_0, & (a_0 + a_1) \cdot b_0, \\ a_0 \cdot b_1, & a_1 \cdot b_1, & (a_0 + a_1) \cdot b_1, \\ a_0 \cdot (b_0 + b_1), & a_1 \cdot (b_0 + b_1), & (a_0 + a_1) \cdot (b_0 + b_1), \\ a_0 \cdot b_2, & a_1 \cdot b_2, & (a_0 + a_1) \cdot b_2, \\ a_0 \cdot (b_0 + b_2), & a_1 \cdot (b_0 + b_2), & (a_0 + a_1) \cdot (b_0 + b_2), \\ a_0 \cdot (b_1 + b_2), & a_1 \cdot (b_1 + b_2), & (a_0 + a_1) \cdot (b_1 + b_2), \\ a_0 \cdot (b_0 + b_1 + b_2), & a_1 \cdot (b_0 + b_1 + b_2), & (a_0 + a_1) \cdot (b_0 + b_1 + b_2) \end{array} \right\}$$

Outline of the talk

- ▶ Problem description
- ▶ Resolution methods
- ▶ Results

Naive algorithm

- ▶ Goal: find the optimal formulae (i.e., with a minimum number of products)
 - enumerate the subsets $\mathcal{W} \subset \mathcal{G}$ of exactly k products which yield a valid formula
 - starting with $k = \text{rk}(\mathcal{T})$, increase k until a solution is found
- ▶ Look for \mathcal{W} such that
 - \mathcal{W} is a set of k generators:

$$\mathcal{W} \subset \mathcal{G} \quad \text{and} \quad \#\mathcal{W} = k$$

- \mathcal{W} linearly generates the coefficients of the results:

$$\mathcal{T} \subset \text{Span } \mathcal{W}$$

Naive algorithm

- ▶ Goal: find the optimal formulae (i.e., with a minimum number of products)
 - enumerate the subsets $\mathcal{W} \subset \mathcal{G}$ of exactly k products which yield a valid formula
 - starting with $k = \text{rk}(\mathcal{T})$, increase k until a solution is found
- ▶ Look for \mathcal{W} such that
 - \mathcal{W} is a set of k generators:

$$\mathcal{W} \subset \mathcal{G} \quad \text{and} \quad \#\mathcal{W} = k$$

- \mathcal{W} linearly generates the coefficients of the results:

$$\mathcal{T} \subset \text{Span } \mathcal{W}$$

- ▶ Naive approach:
 - enumerate the $\binom{\#\mathcal{G}}{k}$ subsets \mathcal{W} of size k
 - for each subset, test whether it generates \mathcal{T} or not

Naive algorithm

- ▶ Goal: find the optimal formulae (i.e., with a minimum number of products)
 - enumerate the subsets $\mathcal{W} \subset \mathcal{G}$ of exactly k products which yield a valid formula
 - starting with $k = \text{rk}(\mathcal{T})$, increase k until a solution is found
- ▶ Look for \mathcal{W} such that
 - \mathcal{W} is a set of k generators:

$$\mathcal{W} \subset \mathcal{G} \quad \text{and} \quad \#\mathcal{W} = k$$

- \mathcal{W} linearly generates the coefficients of the results:

$$\mathcal{T} \subset \text{Span } \mathcal{W}$$

- ▶ Naive approach:
 - enumerate the $\binom{\#\mathcal{G}}{k}$ subsets \mathcal{W} of size k
 - for each subset, test whether it generates \mathcal{T} or not
- ▶ \mathcal{G} has to be finite:
 - look for formulae over finite fields: $K = \mathbb{F}_q$ (typically, $q = 2, 3, 4$)
 - restrict to a finite subset of the generators \mathcal{G} (but search not exhaustive)

Improvement 1: subspaces instead of subsets

- ▶ Drawback of the naive approach: **Distinct subsets** may span the **same subspace**

Improvement 1: subspaces instead of subsets

- ▶ Drawback of the naive approach: Distinct subsets may span the same subspace
- ▶ Look instead for subspaces W of V such that
 - W can be generated by products only: $\text{Span}(W \cap \mathcal{G}) = W$
 - only k products are required: $\dim W = k$
 - W contains the target space spanned by the target vectors: $T = \text{Span } \mathcal{T} \subset W$

Improvement 1: subspaces instead of subsets

- ▶ Drawback of the naive approach: Distinct subsets may span the same subspace
- ▶ Look instead for subspaces W of V such that
 - W can be generated by products only: $\text{Span}(W \cap \mathcal{G}) = W$
 - only k products are required: $\dim W = k$
 - W contains the target space spanned by the target vectors: $T = \text{Span } \mathcal{T} \subset W$
- ▶ Solution space $W \Rightarrow$ several bases $\mathcal{W} \Rightarrow$ one formula per basis.

Improvement 1: subspaces instead of subsets

- ▶ Drawback of the naive approach: Distinct subsets may span the same subspace
- ▶ Look instead for subspaces W of V such that
 - W can be generated by products only: $\text{Span}(W \cap \mathcal{G}) = W$
 - only k products are required: $\dim W = k$
 - W contains the target space spanned by the target vectors: $T = \text{Span } \mathcal{T} \subset W$
- ▶ Solution space $W \Rightarrow$ several bases $\mathcal{W} \Rightarrow$ one formula per basis.
- ▶ No change of the worst case complexity.

Improvement 1: subspaces instead of subsets

- ▶ Look instead for subspaces W of V such that
 - W can be generated by products only: $\text{Span}(W \cap \mathcal{G}) = W$
 - only k products are required: $\dim W = k$
 - W contains the target space spanned by the target vectors: $T = \text{Span } \mathcal{T} \subset W$

Improvement 1: subspaces instead of subsets

- ▶ Look instead for **subspaces** W of V such that
 - W can be **generated by products** only: $\text{Span}(W \cap \mathcal{G}) = W$
 - only k **products** are required: $\dim W = k$
 - W contains the **target space** spanned by the target vectors: $T = \text{Span } \mathcal{T} \subset W$

▶ Algorithm:

```
1: procedure expand_subspace( $W$ )
2:   if  $\dim W = k$  and  $T \subset W$  then
3:      $W$  is a solution
4:   else if  $\dim W < k$  then
5:     for each  $g \in \mathcal{G} \setminus W$  do
6:       expand_subspace( $W \oplus \text{Span}(g)$ )
7:   end procedure
8:
9: expand_subspace( $\{\mathbf{0}\}$ )
```

Improvement 2: expanding the target space

Exploration:

Improvement 2: expanding the target space

Exploration:

- ▶ Choose a vector space W spanned by elements of \mathcal{G} and test if it contains T

Improvement 2: expanding the target space

Exploration:

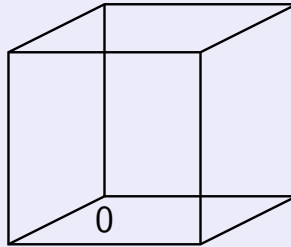
- ▶ ~~Choose a vector space W spanned by elements of \mathcal{G} and test if it contains T~~
- ▶ Choose W containing T and **detect** all the vectors of \mathcal{G} in W . Test if they are enough to form a basis of W

Improvement 2: expanding the target space

Exploration:

- ▶ ~~Choose a vector space W spanned by elements of \mathcal{G} and test if it contains T~~
- ▶ Choose W containing T and **detect** all the vectors of \mathcal{G} in W . Test if they are enough to form a basis of W

Example

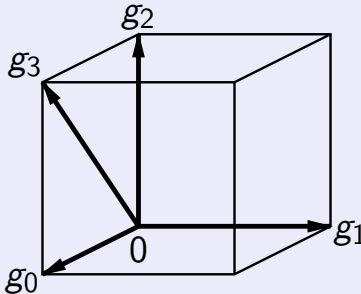


Improvement 2: expanding the target space

Exploration:

- ▶ ~~Choose a vector space W spanned by elements of \mathcal{G} and test if it contains T~~
- ▶ Choose W containing T and **detect** all the vectors of \mathcal{G} in W . Test if they are enough to form a basis of W

Example

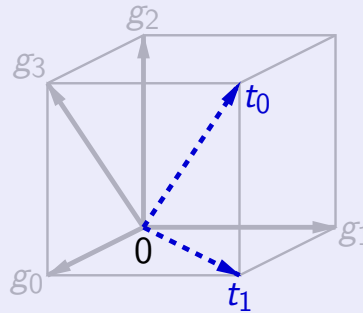


Improvement 2: expanding the target space

Exploration:

- ▶ ~~Choose a vector space W spanned by elements of \mathcal{G} and test if it contains T~~
- ▶ Choose W containing T and **detect** all the vectors of \mathcal{G} in W . Test if they are enough to form a basis of W

Example

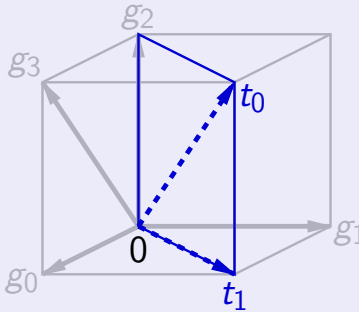


Improvement 2: expanding the target space

Exploration:

- ▶ ~~Choose a vector space W spanned by elements of \mathcal{G} and test if it contains T~~
- ▶ Choose W containing T and **detect** all the vectors of \mathcal{G} in W . Test if they are enough to form a basis of W

Example

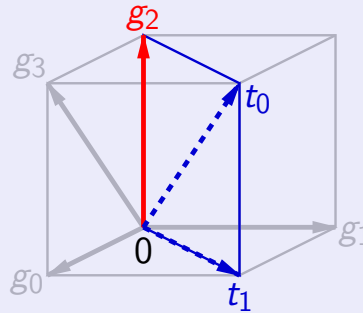


Improvement 2: expanding the target space

Exploration:

- ▶ ~~Choose a vector space W spanned by elements of \mathcal{G} and test if it contains T~~
- ▶ Choose W containing T and **detect** all the vectors of \mathcal{G} in W . Test if they are enough to form a basis of W

Example

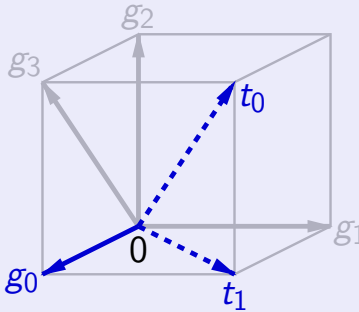


Improvement 2: expanding the target space

Exploration:

- ▶ ~~Choose a vector space W spanned by elements of \mathcal{G} and test if it contains T~~
- ▶ Choose W containing T and **detect** all the vectors of \mathcal{G} in W . Test if they are enough to form a basis of W

Example

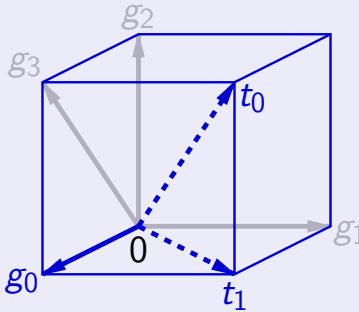


Improvement 2: expanding the target space

Exploration:

- ▶ ~~Choose a vector space W spanned by elements of \mathcal{G} and test if it contains T~~
- ▶ Choose W containing T and **detect** all the vectors of \mathcal{G} in W . Test if they are enough to form a basis of W

Example

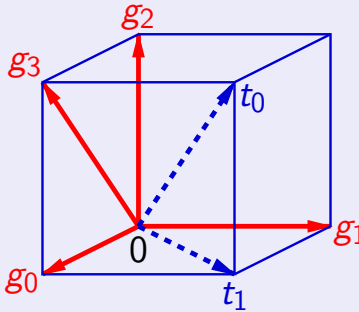


Improvement 2: expanding the target space

Exploration:

- ▶ ~~Choose a vector space W spanned by elements of \mathcal{G} and test if it contains T~~
- ▶ Choose W containing T and **detect** all the vectors of \mathcal{G} in W . Test if they are enough to form a basis of W

Example

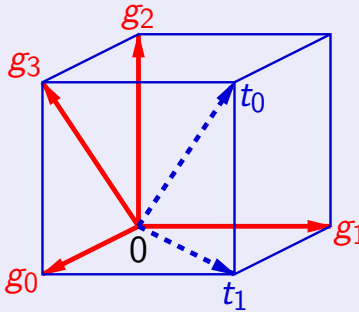


Improvement 2: expanding the target space

Exploration:

- ▶ ~~Choose a vector space W spanned by elements of \mathcal{G} and test if it contains T~~
- ▶ Choose W containing T and **detect** all the vectors of \mathcal{G} in W . Test if they are enough to form a basis of W

Example



Moreover, the Incomplete Basis Theorem allows us to explore only the spaces

$$W = T \oplus \text{Span } \mathcal{W}' \text{ with } \mathcal{W}' \subset \mathcal{G}$$

Improvement 2: expanding the target space

► Modified algorithm:

```
1: procedure expand_subspace( $W$ )
2:   if  $\dim W = k$  and  $T \subset W$  then
3:      $W$  is a solution
4:   else if  $\dim W < k$  then
5:     for each  $g \in \mathcal{G} \setminus W$  do
6:       expand_subspace( $W \oplus \text{Span}(g)$ )
7:   end procedure
8:
9: expand_subspace( $\{\mathbf{0}\}$ )
```


Improvement 2: expanding the target space

► Modified algorithm:

```
1: procedure expand_subspace( $W$ )
2:   if  $\dim W = k$  and  $T \subset W$  then
3:      $W$  is a solution
4:   else if  $\dim W < k$  then
5:     for each  $g \in \mathcal{G} \setminus W$  do
6:       expand_subspace( $W \oplus \text{Span}(g)$ )
7:   end procedure
8:
9: expand_subspace({ $\mathbf{0}$ })
```

Improvement 2: expanding the target space

► Modified algorithm:

```
1: procedure expand_subspace( $W$ )
2:   if  $\dim W = k$  and  $T \subset W$  then
3:      $W$  is a solution
4:   else if  $\dim W < k$  then
5:     for each  $g \in \mathcal{G} \setminus W$  do
6:       expand_subspace( $W \oplus \text{Span}(g)$ )
7:   end procedure
8:
9: expand_subspace( $T$ )
```

Improvement 2: expanding the target space

► Modified algorithm:

```
1: procedure expand_subspace( $W$ )
2:   if  $\dim W = k$  and  $T \in W$  then
3:      $W$  is a solution
4:   else if  $\dim W < k$  then
5:     for each  $g \in \mathcal{G} \setminus W$  do
6:       expand_subspace( $W \oplus \text{Span}(g)$ )
7:   end procedure
8:
9: expand_subspace( $T$ )
```

Improvement 2: expanding the target space

► Modified algorithm:

```
1: procedure expand_subspace( $W$ )
2:   if  $\dim W = k$  and  $\text{rk}(W \cap \mathcal{G}) = k$  then
3:      $W$  is a solution
4:   else if  $\dim W < k$  then
5:     for each  $g \in \mathcal{G} \setminus W$  do
6:       expand_subspace( $W \oplus \text{Span}(g)$ )
7:   end procedure
8:
9: expand_subspace( $T$ )
```

Improvement 2: expanding the target space

► Modified algorithm:

```
1: procedure expand_subspace( $W$ )
2:   if  $\dim W = k$  and  $\text{rk}(W \cap \mathcal{G}) = k$  then
3:      $W$  is a solution
4:   else if  $\dim W < k$  then
5:     for each  $g \in \mathcal{G} \setminus W$  do
6:       expand_subspace( $W \oplus \text{Span}(g)$ )
7:   end procedure
8:
9: expand_subspace( $T$ )
```

Improvement 2: expanding the target space

► Modified algorithm:

```
1: procedure expand_subspace( $W$ )
2:   if  $\dim W = k$  and  $\text{rk}(W \cap \mathcal{G}) = k$  then
3:      $W$  is a solution
4:   else if  $\dim W < k$  then
5:     for each  $g \in \mathcal{G} \setminus W$  do
6:       expand_subspace( $W \oplus \text{Span}(g)$ )
7:   end procedure
8:
9: expand_subspace( $T$ )
```

► Complexity now depends on

$$\begin{pmatrix} \#\mathcal{G} \\ k - \text{rk } T \end{pmatrix}$$

Improvement 2: expanding the target space

► Modified algorithm:

```
1: procedure expand_subspace( $W$ )
2:   if  $\dim W = k$  and  $\text{rk}(W \cap \mathcal{G}) = k$  then
3:      $W$  is a solution
4:   else if  $\dim W < k$  then
5:     for each  $g \in \mathcal{G} \setminus W$  do
6:       expand_subspace( $W \oplus \text{Span}(g)$ )
7:   end procedure
8:
9: expand_subspace( $T$ )
```

► Complexity now depends on

$$\binom{\#\mathcal{G}}{k - \text{rk } T}$$

► For instance for 5×5 -term polynomial multiplication we have $\binom{961}{13-9} = 3.53 \cdot 10^{11}$ instead of $\binom{961}{13} = 8.82 \cdot 10^{28}$.

Example (continued)

2×3 -term polynomial product in $\mathbb{F}_2[X]$

Example (continued)

2×3 -term polynomial product in $\mathbb{F}_2[X]$

- ▶ Targets: $\mathcal{T} = \{a_1b_2, a_1b_1 + a_0b_2, a_0b_1 + a_1b_0, a_0b_0\}$
 - at least $\text{rk}(\mathcal{T}) = 4$ products required

Example (continued)

2×3 -term polynomial product in $\mathbb{F}_2[X]$

- ▶ Targets: $\mathcal{T} = \{a_1b_2, a_1b_1 + a_0b_2, a_0b_1 + a_1b_0, a_0b_0\}$
 - at least $\text{rk}(\mathcal{T}) = 4$ products required
- ▶ Attempt with $k = 4$:
 - $W = \mathcal{T}$
 - $\mathcal{T} \cap \mathcal{G} = \{ a_0 \cdot b_0, a_1 \cdot b_2, (a_0 + a_1) \cdot (b_0 + b_1 + b_2) \}$

Example (continued)

2×3 -term polynomial product in $\mathbb{F}_2[X]$

- ▶ Targets: $\mathcal{T} = \{a_1b_2, a_1b_1 + a_0b_2, a_0b_1 + a_1b_0, a_0b_0\}$
 - at least $\text{rk}(\mathcal{T}) = 4$ products required
- ▶ Attempt with $k = 4$:
 - $W = \mathcal{T}$
 - $\mathcal{T} \cap \mathcal{G} = \{a_0 \cdot b_0, a_1 \cdot b_2, (a_0 + a_1) \cdot (b_0 + b_1 + b_2)\}$
 - $\text{rk}(\mathcal{T} \cap \mathcal{G}) = 3 < k$
 - **no solutions** with $k = 4$ products only

Example (continued)

Attempt with $k = 5$:

▶ Try with $W = T \oplus \text{Span}\{a_0b_1\}$

$$\begin{aligned} \text{▶ } W \cap \mathcal{G} = \{ & a_0 \cdot b_0, & a_1 \cdot b_0, & (a_0 + a_1) \cdot b_0, \\ & a_0 \cdot b_1, & a_1 \cdot b_2, & (a_0 + a_1) \cdot (b_1 + b_2), \\ & a_0 \cdot (b_0 + b_1), & a_1 \cdot (b_0 + b_2), & (a_0 + a_1) \cdot (b_0 + b_1 + b_2) \} \end{aligned}$$

Example (continued)

Attempt with $k = 5$:

▶ Try with $W = T \oplus \text{Span} \{a_0 b_1\}$

▶ $W \cap \mathcal{G} = \{$

$a_0 \cdot b_0,$	$a_1 \cdot b_0,$	$(a_0 + a_1) \cdot b_0,$
$a_0 \cdot b_1,$	$a_1 \cdot b_2,$	$(a_0 + a_1) \cdot (b_1 + b_2),$
$a_0 \cdot (b_0 + b_1),$	$a_1 \cdot (b_0 + b_2),$	$(a_0 + a_1) \cdot (b_0 + b_1 + b_2) \}$

▶ $\text{rk}(W \cap \mathcal{G}) = 5 = k$, W is a solution!

Example (continued)

Attempt with $k = 5$:

▶ Try with $W = T \oplus \text{Span} \{a_0 b_1\}$

▶ $W \cap \mathcal{G} = \left\{ \begin{array}{lll} a_0 \cdot b_0, & a_1 \cdot b_0, & (a_0 + a_1) \cdot b_0, \\ a_0 \cdot b_1, & a_1 \cdot b_2, & (a_0 + a_1) \cdot (b_1 + b_2), \\ a_0 \cdot (b_0 + b_1), & a_1 \cdot (b_0 + b_2), & (a_0 + a_1) \cdot (b_0 + b_1 + b_2) \end{array} \right\}$

▶ $\text{rk}(W \cap \mathcal{G}) = 5 = k$, W is a solution!

▶ $\{a_0 b_0, a_1 b_0, a_0 b_1, a_1 b_2, (a_0 + a_1)(b_1 + b_2)\}$ is a basis of W , and gives a formula

Example (continued)

Attempt with $k = 5$:

▶ Try with $W = T \oplus \text{Span} \{a_0 b_1\}$

▶ $W \cap \mathcal{G} = \left\{ \begin{array}{lll} a_0 \cdot b_0, & a_1 \cdot b_0, & (a_0 + a_1) \cdot b_0, \\ a_0 \cdot b_1, & a_1 \cdot b_2, & (a_0 + a_1) \cdot (b_1 + b_2), \\ a_0 \cdot (b_0 + b_1), & a_1 \cdot (b_0 + b_2), & (a_0 + a_1) \cdot (b_0 + b_1 + b_2) \end{array} \right\}$

▶ $\text{rk}(W \cap \mathcal{G}) = 5 = k$, W is a solution!

▶ $\{a_0 b_0, a_1 b_0, a_0 b_1, a_1 b_2, (a_0 + a_1)(b_1 + b_2)\}$ is a basis of W , and gives a formula

▶ 3 such solution spaces \Rightarrow 162 bases \Rightarrow 162 formulae

A generic algorithm

- ▶ This algorithm works for **every bilinear maps**:
 - short products, middle products, cross products
 - multiplication in complexes, quaternions, field extensions, matrices
 - multiplication of **sparse** polynomials and matrices
 - etc.

A generic algorithm

- ▶ This algorithm works for **every bilinear maps**:
 - short products, middle products, cross products
 - multiplication in complexes, quaternions, field extensions, matrices
 - multiplication of **sparse** polynomials and matrices
 - etc.
- ▶ The **quadratic forms** form a vector space too.
 - simply requires extending the definition of \mathcal{G} :

$$\mathcal{G} = \{ (\sum \alpha_i a_i) \cdot (\sum \alpha'_i a_i) \mid (\alpha_0, \dots, \alpha_{n-1}) \preceq_{\text{lex}} (\alpha'_0, \dots, \alpha'_{n-1}) \} \setminus \{0\}$$

- example: **squaring of a 2-term polynomial** in $\mathbb{F}_3[X]$

$$\mathcal{G} = \{ a_0 \cdot a_0, \\ a_0 \cdot a_1, \quad a_1 \cdot a_1, \\ a_0 \cdot (a_0 + a_1), \quad a_1 \cdot (a_0 + a_1), \quad (a_0 + a_1) \cdot (a_0 + a_1), \\ a_0 \cdot (a_0 - a_1), \quad a_1 \cdot (a_0 - a_1), \quad (a_0 + a_1) \cdot (a_0 - a_1), \quad (a_0 - a_1) \cdot (a_0 - a_1) \}$$

Outline of the talk

- ▶ Problem description
- ▶ Resolution methods
- ▶ **Results**

$n \times m$ -term polynomial multiplication

Ring	$n \times m$	$\#\mathcal{G}$	k	# of tests	# of solutions	# of formulae	Calculation time [s]
$F_2[X]$	2×2	9	3	1	1	1	0.00
	3×3	49	6	9	3	9	0.00
	4×4	225	9	$6.60 \cdot 10^3$	4	4	0.03
	5×5	961	13	$9.65 \cdot 10^9$	27	27	$2.28 \cdot 10^5$
	6×6	3969	14	$4.37 \cdot 10^9$	—	—	$6.03 \cdot 10^5$
	6×6	(Sym.) 63	17	$8.08 \cdot 10^6$	6	54	17.7
	7×7	(Sym.) 127	22	$3.38 \cdot 10^{12}$	2 618	19 550	$1.59 \cdot 10^7$
$F_3[X]$	2×2	16	3	1	1	4	0.00
	3×3	169	6	24	22	1 493	0.00
	4×4	1 600	9	$4.11 \cdot 10^5$	726	50 640	14.9
	5×5	14 641	11	$4.89 \cdot 10^7$	—	—	$4.02 \cdot 10^4$
		(Sym.) 121	12	$3.93 \cdot 10^4$	31	6 460	0.14
	6×6	(Sym.) 364	15	$2.37 \cdot 10^8$	4	1 024	$3.79 \cdot 10^3$
	7×7	(Sym.) 1 093	17	$2.69 \cdot 10^{10}$	—	—	$1.50 \cdot 10^6$

$n \times m$ -term polynomial multiplication

Ring	$n \times m$	$\#\mathcal{G}$	k	# of tests	# of solutions	# of formulae	Calculation time [s]
$F_2[X]$	2×2	9	3	1	1	1	0.00
	3×3	49	6	9	3	9	0.00
	4×4	225	9	$6.60 \cdot 10^3$	4	4	0.03
	5×5	961	13	$9.65 \cdot 10^9$	27	27	$2.28 \cdot 10^5$
	6×6	3969	14	$4.37 \cdot 10^9$	—	—	$6.03 \cdot 10^5$
	6×6	(Sym.) 63	17	$8.08 \cdot 10^6$	6	54	17.7
	7×7	(Sym.) 127	22	$3.38 \cdot 10^{12}$	2 618	19 550	$1.59 \cdot 10^7$
$F_3[X]$	2×2	16	3	1	1	4	0.00
	3×3	169	6	24	22	1 493	0.00
	4×4	1 600	9	$4.11 \cdot 10^5$	726	50 640	14.9
	5×5	14 641	11	$4.89 \cdot 10^7$	—	—	$4.02 \cdot 10^4$
		(Sym.) 121	12	$3.93 \cdot 10^4$	31	6 460	0.14
	6×6	(Sym.) 364	15	$2.37 \cdot 10^8$	4	1 024	$3.79 \cdot 10^3$
	7×7	(Sym.) 1 093	17	$2.69 \cdot 10^{10}$	—	—	$1.50 \cdot 10^6$

$n \times m$ -term polynomial multiplication

Ring	$n \times m$	$\#\mathcal{G}$	k	# of tests	# of solutions	# of formulae	Calculation time [s]
$F_2[X]$	2×2	9	3	1	1	1	0.00
	3×3	49	6	9	3	9	0.00
	4×4	225	9	$6.60 \cdot 10^3$	4	4	0.03
	5×5	961	13	$9.65 \cdot 10^9$	27	27	$2.28 \cdot 10^5$
	6×6	3969	14	$4.37 \cdot 10^9$	—	—	$6.03 \cdot 10^5$
	6×6	(Sym.) 63	17	$8.08 \cdot 10^6$	6	54	17.7
	7×7	(Sym.) 127	22	$3.38 \cdot 10^{12}$	2618	19550	$1.59 \cdot 10^7$
$F_3[X]$	2×2	16	3	1	1	4	0.00
	3×3	169	6	24	22	1493	0.00
	4×4	1600	9	$4.11 \cdot 10^5$	726	50640	14.9
	5×5	14641	11	$4.89 \cdot 10^7$	—	—	$4.02 \cdot 10^4$
		(Sym.) 121	12	$3.93 \cdot 10^4$	31	6460	0.14
	6×6	(Sym.) 364	15	$2.37 \cdot 10^8$	4	1024	$3.79 \cdot 10^3$
	7×7	(Sym.) 1093	17	$2.69 \cdot 10^{10}$	—	—	$1.50 \cdot 10^6$

$n \times m$ -term polynomial multiplication

Ring	$n \times m$	$\#\mathcal{G}$	k	# of tests	# of solutions	# of formulae	Calculation time [s]
$F_2[X]$	2×2	9	3	1	1	1	0.00
	3×3	49	6	9	3	9	0.00
	4×4	225	9	$6.60 \cdot 10^3$	4	4	0.03
	5×5	961	13	$9.65 \cdot 10^9$	27	27	$2.28 \cdot 10^5$
	6×6	3969	14	$4.37 \cdot 10^9$	—	—	$6.03 \cdot 10^5$
	6×6	(Sym.) 63	17	$8.08 \cdot 10^6$	6	54	17.7
	7×7	(Sym.) 127	22	$3.38 \cdot 10^{12}$	2 618	19 550	$1.59 \cdot 10^7$
$F_3[X]$	2×2	16	3	1	1	4	0.00
	3×3	169	6	24	22	1 493	0.00
	4×4	1 600	9	$4.11 \cdot 10^5$	726	50 640	14.9
	5×5	14 641	11	$4.89 \cdot 10^7$	—	—	$4.02 \cdot 10^4$
		(Sym.) 121	12	$3.93 \cdot 10^4$	31	6 460	0.14
	6×6	(Sym.) 364	15	$2.37 \cdot 10^8$	4	1 024	$3.79 \cdot 10^3$
	7×7	(Sym.) 1 093	17	$2.69 \cdot 10^{10}$	—	—	$1.50 \cdot 10^6$

$n \times m$ -term polynomial multiplication

Ring	$n \times m$	$\#\mathcal{G}$	k	# of tests	# of solutions	# of formulae	Calculation time [s]
$F_2[X]$	2×2	9	3	1	1	1	0.00
	3×3	49	6	9	3	9	0.00
	4×4	225	9	$6.60 \cdot 10^3$	4	4	0.03
	5×5	961	13	$9.65 \cdot 10^9$	27	27	$2.28 \cdot 10^5$
	6×6	3969	14	$4.37 \cdot 10^9$	—	—	$6.03 \cdot 10^5$
	6×6	(Sym.) 63	17	$8.08 \cdot 10^6$	6	54	17.7
	7×7	(Sym.) 127	22	$3.38 \cdot 10^{12}$	2 618	19 550	$1.59 \cdot 10^7$
$F_3[X]$	2×2	16	3	1	1	4	0.00
	3×3	169	6	24	22	1 493	0.00
	4×4	1 600	9	$4.11 \cdot 10^5$	726	50 640	14.9
	5×5	14 641	11	$4.89 \cdot 10^7$	—	—	$4.02 \cdot 10^4$
		(Sym.) 121	12	$3.93 \cdot 10^4$	31	6 460	0.14
	6×6	(Sym.) 364	15	$2.37 \cdot 10^8$	4	1 024	$3.79 \cdot 10^3$
	7×7	(Sym.) 1 093	17	$2.69 \cdot 10^{10}$	—	—	$1.50 \cdot 10^6$

Example of symmetric product: $(a_0 + a_2 + a_5) \cdot (b_0 + b_2 + b_5)$

$n \times m$ -term polynomial multiplication

Ring	$n \times m$	$\#\mathcal{G}$	k	# of tests	# of solutions	# of formulae	Calculation time [s]
$F_2[X]$	2×2	9	3	1	1	1	0.00
	3×3	49	6	9	3	9	0.00
	4×4	225	9	$6.60 \cdot 10^3$	4	4	0.03
	5×5	961	13	$9.65 \cdot 10^9$	27	27	$2.28 \cdot 10^5$
	6×6	3969	14	$4.37 \cdot 10^9$	—	—	$6.03 \cdot 10^5$
	6×6	(Sym.) 63	17	$8.08 \cdot 10^6$	6	54	17.7
	7×7	(Sym.) 127	22	$3.38 \cdot 10^{12}$	2 618	19 550	$1.59 \cdot 10^7$
$F_3[X]$	2×2	16	3	1	1	4	0.00
	3×3	169	6	24	22	1 493	0.00
	4×4	1 600	9	$4.11 \cdot 10^5$	726	50 640	14.9
	5×5	14 641	11	$4.89 \cdot 10^7$	—	—	$4.02 \cdot 10^4$
		(Sym.) 121	12	$3.93 \cdot 10^4$	31	6 460	0.14
	6×6	(Sym.) 364	15	$2.37 \cdot 10^8$	4	1 024	$3.79 \cdot 10^3$
	7×7	(Sym.) 1 093	17	$2.69 \cdot 10^{10}$	—	—	$1.50 \cdot 10^6$

Multiplication in small finite-field extensions

Finite field	$\#\mathcal{G}$	k	# of tests	# of solutions	# of formulae	Calculation time [s]
\mathbf{F}_{2^2}	9	3	3	3	3	0.00
\mathbf{F}_{2^3}	49	6	$7.03 \cdot 10^3$	105	147	0.01
\mathbf{F}_{2^4}	225	9	$2.57 \cdot 10^9$	2025	2025	$1.13 \cdot 10^4$
\mathbf{F}_{2^5}	961	9	$3.10 \cdot 10^{10}$	—	—	$8.11 \cdot 10^5$
	(Sym.) 31	13	$3.49 \cdot 10^6$	2015	2015	6.24
\mathbf{F}_{2^6}	(Sym.) 63	15	$2.21 \cdot 10^{10}$	21	21	$6.63 \cdot 10^4$
\mathbf{F}_{2^7}	(Sym.) 127	15	$1.34 \cdot 10^{12}$	—	—	$6.17 \cdot 10^6$
\mathbf{F}_{3^2}	16	3	3	4	16	0.00
\mathbf{F}_{3^3}	169	6	$2.42 \cdot 10^5$	11 843	105 963	1.08
\mathbf{F}_{3^4}	1 600	8	$2.27 \cdot 10^{11}$	—	—	$1.08 \cdot 10^7$
	(Sym.) 40	9	$1.10 \cdot 10^5$	234	615 240	0.45
\mathbf{F}_{3^5}	(Sym.) 121	11	$2.66 \cdot 10^9$	121	121	$1.45 \cdot 10^4$
\mathbf{F}_{3^6}	(Sym.) 364	12	$3.01 \cdot 10^{12}$	—	—	$4.50 \cdot 10^7$

Multiplication in small finite-field extensions

Finite field	$\#\mathcal{G}$	k	# of tests	# of solutions	# of formulae	Calculation time [s]
\mathbf{F}_{2^2}	9	3	3	3	3	0.00
\mathbf{F}_{2^3}	49	6	$7.03 \cdot 10^3$	105	147	0.01
\mathbf{F}_{2^4}	225	9	$2.57 \cdot 10^9$	2025	2025	$1.13 \cdot 10^4$
\mathbf{F}_{2^5}	961	9	$3.10 \cdot 10^{10}$	—	—	$8.11 \cdot 10^5$
	(Sym.) 31	13	$3.49 \cdot 10^6$	2015	2015	6.24
\mathbf{F}_{2^6}	(Sym.) 63	15	$2.21 \cdot 10^{10}$	21	21	$6.63 \cdot 10^4$
\mathbf{F}_{2^7}	(Sym.) 127	15	$1.34 \cdot 10^{12}$	—	—	$6.17 \cdot 10^6$
\mathbf{F}_{3^2}	16	3	3	4	16	0.00
\mathbf{F}_{3^3}	169	6	$2.42 \cdot 10^5$	11 843	105 963	1.08
\mathbf{F}_{3^4}	1 600	8	$2.27 \cdot 10^{11}$	—	—	$1.08 \cdot 10^7$
	(Sym.) 40	9	$1.10 \cdot 10^5$	234	615 240	0.45
\mathbf{F}_{3^5}	(Sym.) 121	11	$2.66 \cdot 10^9$	121	121	$1.45 \cdot 10^4$
\mathbf{F}_{3^6}	(Sym.) 364	12	$3.01 \cdot 10^{12}$	—	—	$4.50 \cdot 10^7$

Conclusion

- ▶ General algorithm (polynomials, matrices, squaring, etc.)
- ▶ Method that **proves lower bounds** on the number of subproducts (no heuristics used)
- ▶ Gives **all formulae**
 - Provides **new formulae** that cannot be found with previous methods
 - We can cherry-pick the one with **minimum number of additions and scalar multiplications**

Conclusion

- ▶ **General** algorithm (polynomials, matrices, squaring, etc.)
- ▶ Method that **proves lower bounds** on the number of subproducts (no heuristics used)
- ▶ Gives **all formulae**
 - Provides **new formulae** that cannot be found with previous methods
 - We can cherry-pick the one with **minimum number of additions and scalar multiplications**
- ▶ Work in progress and perspectives
 - **Lifting formulae** for higher-characteristic or characteristic-0 fields
 - Find formulae for **your favorite** bilinear application!

3×3 polynomial multiplication in odd characteristic

Compute the following products:

$$\begin{aligned}g_0 &= a_0 \cdot b_0 \\g_1 &= a_2 \cdot b_2 \\g_2 &= (a_0 + a_1) \cdot (b_0 + b_2) \\g_3 &= (a_0 + a_2) \cdot (b_1 + b_2) \\g_4 &= (a_1 + a_2) \cdot (b_0 + b_1) \\g_5 &= (a_0 + a_1 + a_2) \cdot (b_0 + b_1 + b_2).\end{aligned}$$

Reconstruct the coefficients of the result.

$$(a_0 + a_1X + a_2X^2) \cdot (b_0 + b_1X + b_2X^2) = g_1X^4 + (g_0 + g_3 + g_4 + g_5)X^3 + (g_2 + g_3 + g_5)X^2 + (g_1 + g_2 + g_4 + g_5)X + g_0$$